

# SANYO Semiconductors DATA SHEET



# **CMOSIC** LC87F5G32A — FROM 32K byte, RAM 1024 byte on-chip 8-bit 1-chip Microcontroller

### **Overview**

The SANYO LC87F5G32A is an 8-bit microcomputer that, centered around a CPU running at a minimum bus cycle time of 100ns, integrates on a single chip a number of hardware features such as 32K-byte flash ROM (onboard programmable), 1024-byte RAM, an on-chip debugger, sophisticated 16-bit timers/counters (may be divided into 8-bit timers), a 16-bit timer/counter (may be divided into 8-bit timers/counters or 8-bit PWMs), four 8-bit timers with a prescaler, a base timer serving as a time-of-day clock, a high-speed clock counter, a synchronous SIO interface (with automatic block transmission/reception capabilities), an asynchronous/synchronous SIO interface, a UART interface (full duplex), a 12-bit/8-bit 12-channel AD converter, two 12-bit PWM channels, a system clock frequency divider, and a 22-source 10-vector interrupt feature.

### Features

### ■Flash ROM

- Capable of on-board-programming with wide range, 3.0 to 5.5V, of voltage source.
- Block-erasable in 128 byte units
- 32768 × 8-bits (LC87F5G32A)

### ■RAM

• 1024 × 9 bits (LC87F5G32A)

### ■Minimum Bus Cycle

• 100ns (10MHz)

Note : The bus cycle time here refers to the ROM read speed.

### ■Minimum Instruction Cycle Time

• 300ns (10MHz)

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### Ports • Normal withstand voltage I/O ports Ports whose I/O direction can be designated in 1-bit units 30 (P1n,P2n,P30 to P36,P70 to P73,PWM0,PWM1,XT2) Ports whose I/O direction can be designated in 4-bit units 8 (P0n) • Normal withstand voltage input port 1 (XT1) 2 (CF1, CF2) · Dedicated oscillator ports • Reset pins 1 (RES) • Power pins 6 (VSS1 to 3, VDD1 to 3) ■Timers • Timer 0: 16-bit timer/counter with a capture register. Mode 0: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register) $\times$ 2-channels Mode 1: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register) + 8-bit counter (with an 8-bit capture register) Mode 2: 16-bit timer with an 8-bit programmable prescaler (with a 16-bit capture register) Mode 3: 16-bit counter (with a 16-bit capture register) • Timer 1: 16-bit timer/counter that supports PWM/toggle outputs Mode 0: 8-bit timer with an 8-bit prescaler (with toggle outputs) + with an 8-bit prescaler 8-bit timer/counter (with toggle outputs) Mode 1: 8-bit PWM with an 8-bit prescaler × 2-channels Mode 2: 16-bit timer/counter with an 8-bit prescaler (with toggle outputs) (toggle outputs also possible from the lower-order 8-bits) Mode 3: 16-bit timer with an 8-bit prescaler (with toggle outputs) (the lower-order 8-bits can be used as PWM.) • Timer 4: 8-bit timer with a 6-bit prescaler • Timer 5: 8-bit timer with a 6-bit prescaler • Timer 6: 8-bit timer with a 6-bit prescaler (with toggle outputs) • Timer 7: 8-bit timer with a 6-bit prescaler (with toggle outputs) • Base timer 1) The clock is selectable from the subclock (32.768kHz crystal oscillation), system clock, and timer 0 prescaler output. 2) Interrupts programmable in 5 different time schemes ■High-speed Clock Counter 1) Can count clocks with a maximum clock rate of 20MHz (at a main clock of 10MHz). 2) Can generate output real-time.

### ■SIO

- SIO0: 8-bit synchronous serial interface
  - 1) LSB first/MSB first mode selectable
  - 2) Built-in 8-bit baudrate generator (maximum transfer clock cycle=4/3 tCYC)
  - 3) Automatic continuous data transmission (1 to 256-bits, specifiable in 1 bit units, suspension and resumption of data transmission possible in 1 byte units)
- SIO1: 8-bit asynchronous/synchronous serial interface
  - Mode 0: Synchronous 8-bit serial I/O (2- or 3-wire configuration, 2 to 512 tCYC transfer clocks)
  - Mode 1: Asynchronous serial I/O (half-duplex, 8 data bits, 1 stop bit, 8 to 2048 tCYC baudrates)
  - Mode 2: Bus mode 1 (start bit, 8 data bits, 2 to 512 tCYC transfer clocks)

Mode 3: Bus mode 2 (start detect, 8 data bits, stop detect)

- ■UART
  - Full duplex
  - 7/8/9 bit data bits selectable
  - 1stop bit (2-bit in continuous data transmission)
  - Built-in baudrate generator

### ■AD Converter: 12-bits/8-bits × 12-channels

- 12-bits/8-bits AD converter selectable
- Automatic reference voltage generation controllable

### ■PWM: Multifrequency 12-bit PWM × 2-channels

Remote Control Receiver Circuit (sharing pins with P73, INT3, and T0IN)

- Noise rejection function (noise filter time constant selectable from 1 tCYC, 32 tCYC, and 128 tCYC)
- ■Watchdog Timer
  - External RC watchdog timer
  - Interrupt and reset signals selectable

### ■Interrupts

- 22 sources, 10 vector addresses
- 1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.
- 2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address takes precedence.

No.	Vector Address	Level	Interrupt Source
1	00003H	X or L	INTO
2	0000BH	X or L	INT1
3	00013H	H or L	INT2/T0L/INT4
4	0001BH	H or L	INT3/INT5/base timer
5	00023H	H or L	тон
6	0002BH	H or L	T1L/T1H
7	00033H	H or L	SIO0/UART1 receive
8	0003BH	H or L	SIO1/UART1 transmit
9	00043H	H or L	ADC/T6/T7
10	0004BH	H or L	Port 0/T4/T5/PWM0, PWM1

• Priority Levels: X > H > L

• Of interrupts of the same level, the one with the smallest vector address takes precedence.

Subroutine Stack Levels: 512 levels (the stack is allocated in RAM.)

■High-speed Multiplication/Division Instructions

- 16-bits  $\times$  8-bits (5 tCYC execution time)
- 24-bits  $\times$  16-bits (12 tCYC execution time)
- 16-bits  $\div$  8-bits (8 tCYC execution time)
- 24-bits  $\div$  16-bits (12 tCYC execution time)

■Oscillation Circuits

- RC oscillation circuit (internal): For system clock
- CF oscillation circuit: Crystal oscillation circuit:

- For system clock, with internal Rf
- For low-speed system clock, with internal Rf
- Frequency variable RC oscillation circuit (internal): For system clock

### ■System Clock Divider Function

• Can run on low current.

• The minimum instruction cycle selectable from 300ns, 600ns, 1.2µs, 2.4µs, 4.8µs, 9.6µs, 19.2µs, 38.4µs, and 76.8µs (at a main clock rate of 10MHz).

■Standby Function

- HALT mode : Halts instruction execution while allowing the peripheral circuits to continue operation.
- 1) Oscillation is not halted automatically.
- 2) Canceled by a system reset or occurrence of an interrupt.
- HOLD mode : Suspends instruction execution and the operation of the peripheral circuits.
- 1) The CF, RC, and crystal oscillators automatically stop operation.
- 2) There are three ways of resetting the HOLD mode.
  - (1) Setting the reset pin to the lower level.
  - (2) Setting at least one of the INTO, INT1, INT2, INT4, and INT5 pins to the specified level.
  - (3) Having an interrupt source established at port 0.
- X'tal HOLD mode : Suspends instruction execution and the operation of the peripheral circuits except the base timer.
- 1) The CF and RC oscillators automatically stop operation.
- 2) The state of crystal oscillation established when the X'tal HOLD mode is entered is retained.
- 3) There are four ways of resetting the X'tal HOLD mode.
  - (1) Setting the reset pin to the low level.
  - (2) Setting at least one of the INT0, INT1, INT2, INT4, and INT5 pins to the specified level.
  - (3) Having an interrupt source established at port.
  - (4) Having an interrupt source established in the base timer circuit.
- ■Onchip Debugger
  - Supports software debugging with the IC mounted on the target board.

■Package Form

- QIP48E(14×14): "Lead-free type"
- SQFP48(7×7): "Lead-free type"

### ■Development Tools

• Evaluation chip: LC87EV690

• Emulator: EVA62S + ECB876600D + SUB875G00 + POD48QFP

- ICE-B877300 + SUB875G00 + POD48QFP
- Onchip debugger: TCB87 TypeA + LC87F5G32A TCB87 TypeB + LC87F5G32A

### ■Flash ROM Programming boards

Package	Programming boards
QIP48E(14×14)	W87F55256Q
SQFP48(7×7)	W87F55256SQ

### ■Flash ROM programmer

Maker	Model		Supported version (Note)	Device
Flash Support Group, Inc.	Single	AF9708/AF9709/ AF9709B	After 02.40	
(Formerly Ando Electric Co., Ltd.)	Cong	AF9723 (Main body)	After 02.04	LC87F5G32A FAST
	Gang	AF9833 (Unit)	After 01.84	
SANYO SK		SKK (SANYO FWS)	After 1.02C (Install CD)	LC87F5G32A

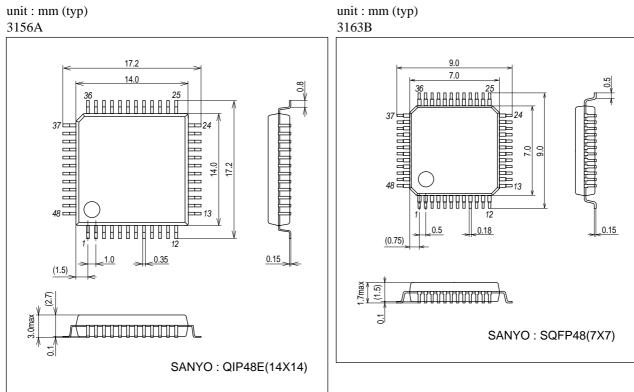
Note: Please check the latest version.

■Same package and pin assignment as mask ROM version.

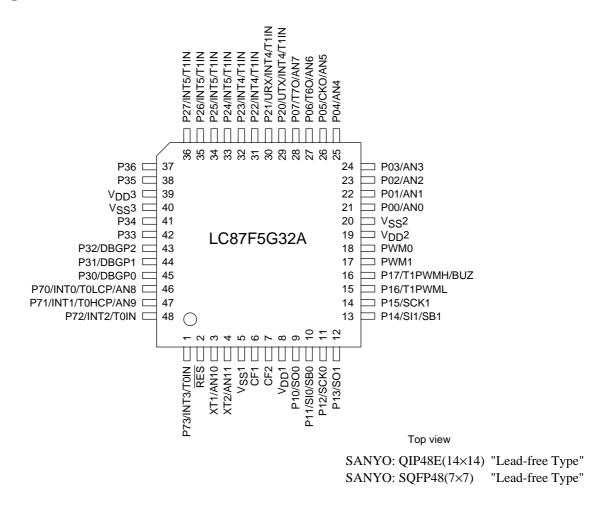
- 1) LC875G00 series options can be set by using flash ROM data. Thus the board used for mass production can be used for debugging and evaluation without modifications.
- 2) If the program for the mask ROM version is used, the usable ROM/RAM capacity is the same as the mask ROM version.

**Package Dimensions** 

### Package Dimensions



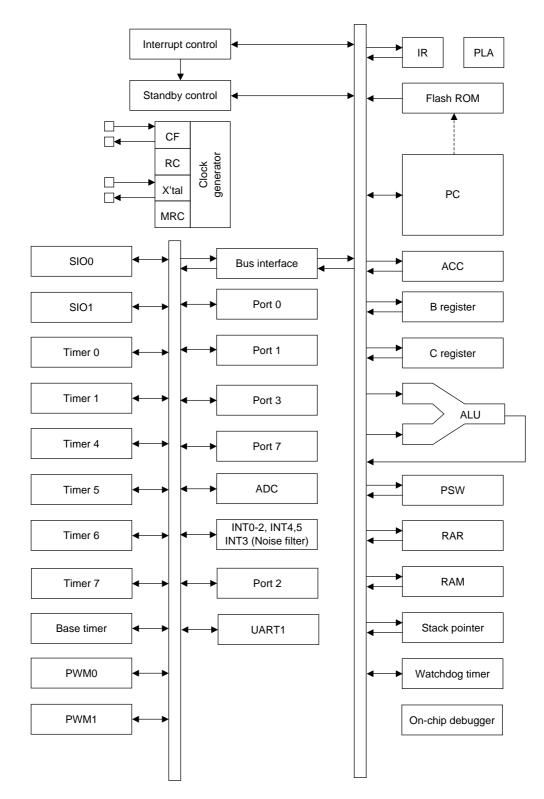
### **Pin Assignment**



SQFP/QIP	NAME
1	P73/INT3/T0IN
2	RES
3	XT1/AN10
4	XT2/AN11
5	V <sub>SS</sub> 1
6	CF1
7	CF2
8	V <sub>DD</sub> 1
9	P10/SO0
10	P11/SI0/SB0
11	P12/SCK0
12	P13/SO1
13	P14/SI1/SB1
14	P15/SCK1
15	P16/T1PWML
16	P17/T1PWMH/BUZ
17	PWM1
18	PWM0
19	V <sub>DD</sub> 2
20	V <sub>SS</sub> 2
21	P00/AN0
22	P01/AN1
23	P02/AN2
24	P03/AN3

SQFP/QIP	NAME			
25	P04/AN4			
26	P05/CKO/AN5			
27	P06/T6O/AN6			
28	P07/T7O/AN7			
29	P20/UTX/INT4/T1IN			
30	P21/URX/INT4/T1IN			
31	P22/INT4/T1IN			
32	P23/INT4/T1IN			
33	P24/INT5/T1IN			
34	P25/INT5/T1IN			
35	P26/INT5/T1IN			
36	P27/INT5/T1IN			
37	P36			
38	P35			
39	V <sub>DD</sub> 3			
40	V <sub>SS</sub> 3			
41	P34			
42	P33			
43	P32/DBGP2			
44	P31/DBGP1			
45	P30/DBGP0			
46	P70/INT0/T0LCP/AN8			
47	P71/INT1/T0HCP/AN9			
48	P72/INT2/T0IN			

# System Block Diagram



# **Pin Function Chart**

Continued on next page.

Pin Name	I/O			Descr	iption			Option	
Port 3	I/O	• 7-bit I/O port							
P30 to P36		<ul> <li>I/O specifiable</li> </ul>	in 1-bit units						
		Pull-up resisto	rs can be turned	on and off in 1-bit	units				
		<ul> <li>Shared pins</li> </ul>							
		On-chip debug	ger pins: DBGP0	) to DBGP2 (P30 t	o P32)				
Port 7	I/O	• 4-bit I/O port						No	
P70 to P73		<ul> <li>I/O specifiable</li> </ul>	in 1-bit units						
		<ul> <li>Pull-up resisto</li> </ul>	rs can be turned	on and off in 1-bit	units				
		<ul> <li>Shared pins</li> </ul>							
		AD converter i	nput port : AN8 (I	P70), AN9 (P71)					
		P70: INT0 inp	ut/HOLD reset inp	out/timer 0L captu	e input/watchdog	timer output			
		P71: INT1 inp	ut/HOLD reset inp	out/timer 0H captu	re input				
		P72: INT2 inp	ut/HOLD reset inp	out/timer 0 event in	put/timer 0L capt	ure input			
	P73: INT3 input (with noise filter)/timer 0 event input/timer 0H capture input								
		Interrupt acknow	vledge type	1		1			
			Rising	Falling	Rising & Falling	H level	L level		
		INT0	enable	enable	disable	enable	enable		
		INT0 INT1	enable	enable	disable	enable	enable		
		INT2	enable	enable	enable	disable	disable		
		INT3	enable	enable	enable	disable	disable		
			onabio	enable	onabio	dicable	dicable		
PWM0, PWM1	I/O	• PWM0 and PV	VM1 output ports					No	
		General-purpo	se I/O available						
RES	Input	Reset pin						No	
XT1	Input	• 32.768kHz cry	stal oscillator inp	ut pin				No	
		Shared pins		-					
		General-purpose input port							
	AD converter input port: AN10								
		Must be conne	Must be connected to V <sub>DD</sub> 1 if not to be used						
XT2	I/O	• 32.768kHz cry	stal oscillator out	put pin				No	
		Shared pins							
		General-purpo	se I/O port						
		AD converter i	nput port: AN11						
		Must be set fo	r oscillation and k	ept open if not to	be used				
CF1	Input	Ceramic resona	tor input pin					No	
CF2	Output	Ceramic resona	tor output pin					No	

# **Port Output Types**

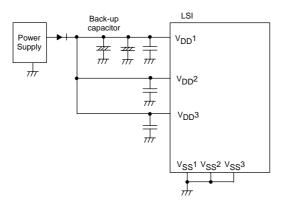
The table below lists the types of port outputs and the presence/absence of a pull-up resistor. Data can be read into any input port even if it is in the output mode.

Port Name	Option Selected in Units of	Option Type	Output Type	Pull-up Resistor
P00 to P07	1-bit	1	CMOS	Programmable (Note 1)
		2	Nch-open drain	No
P10 to P17	1-bit	1	CMOS	Programmable
	-	2	Nch-open drain	Programmable
P20 to P27	1-bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
P30 to P36	1-bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
P70	-	No	Nch-open drain	Programmable
P71 to P73	-	No	CMOS	Programmable
PWM0, PWM1	-	No	CMOS	No
XT1	-	No	Input for 32.768kHz crystal oscillator	No
			(Input only)	
XT2	-	No	Output for 32.768kHz crystal oscillator	No
			(Nch-open drain when in general-purpose	
			output mode)	

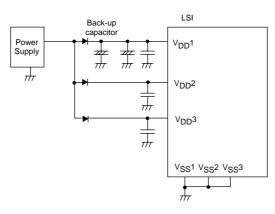
Note 1: Programmable pull-up resistor of Port 0 is specified in nibble units (P00 to P03, P04 to P07).

Note: To reduce  $V_{DD}$  signal noise and to increase the duration of the backup battery supply,  $V_{SS}1$ ,  $V_{SS}2$ , and  $V_{SS}3$  should connect to each other and they should also be grounded.

Example 1: During backup in hold mode, port output 'H' level is supplied from the back-up capacitor.



Example 2: During backup in hold mode, output is not held high and its value in unsettled.



	Parameter	Symbol	Pin/Remarks	Conditions			Spe	ecification	
					V <sub>DD</sub> [V]	min	typ	max	unit
	ximum supply tage	V <sub>DD</sub> max	V <sub>DD</sub> 1, V <sub>DD</sub> 2, V <sub>DD</sub> 3	V <sub>DD</sub> 1=V <sub>DD</sub> 2=V <sub>DD</sub> 3		-0.3		+6.5	
Inp	ut voltage	VI	XT1, CF1			-0.3		V <sub>DD</sub> +0.3	V
	ut/output tage	VIO	Ports 0, 1, 2, 3 Port 7, PWM0, PWM1, XT2			-0.3		V <sub>DD</sub> +0.3	
	Peak output current	IOPH(1)	Ports 0, 1, 2, 3	CMOS output select Per 1 applicable pin		-10			
		IOPH(2)	PWM0, PWM1	CMOS output select Per 1 applicable pin		-20			
		IOPH(3)	Ports P71 to P73	Per 1 applicable pin		-5			
Ч	Mean output current	IOMH(1)	Ports 0, 1, 2, 3	CMOS output select Per 1 applicable pin		-7.5			
t currer	(Note 1-1)	IOMH(2)	PWM0, PWM1	CMOS output select Per 1 applicable pin		-15			
High level output current		IOMH(3)	Ports P71 to P73	Per 1 applicable pin		-3			
	Total output	ΣIOAH(1)	Ports P71 to P73	Total of all applicable pins		-10			
, al r	current	ΣIOAH(2)	Port 0	Total of all applicable pins		-25			
High		ΣΙΟΑΗ(3)	Ports 1, PWM0, PWM1	Total of all applicable pins		-25			
		ΣIOAH(4)	Ports 0, 1 PWM0, PWM1	Total of all applicable pins		-45			
		ΣIOAH(5)	Ports 2, P35, P36	Total of all applicable pins		-25			
		ΣIOAH(6)	Ports P30 to P34	Total of all applicable pins		-25			
		ΣIOAH(7)	Ports 2, 3	Total of all applicable pins		-45			
	Peak output current	IOPL(1)	Ports P02 to P07 Ports 1, 2, 3 PWM0, PWM1	Per 1 applicable pin				20	mA
		IOPL(2)	Ports P00, P01	Per 1 applicable pin				30	
		IOPL(3)	Port 7, XT2	Per 1 applicable pin				10	
ent	Mean output current (Note 1-1)	IOML(1)	Ports P02 to P07 Ports 1, 2, 3 PWM0, PWM1	Per 1 applicable pin				15	
put current	. ,	IOML(2)	Ports P00, P01	Per 1 applicable pin				20	
put		IOML(3)	Port 7, XT2	Per 1 applicable pin				7.5	
i oui	Total output	ΣIOAL(1)	Port 7, XT2	Total of all applicable pins				15	
leve	current	ΣIOAL(2)	Port 0	Total of all applicable pins				45	
Low level ou		ΣIOAL(3)	Ports 1, PWM0, PWM1	Total of all applicable pins				45	
		ΣIOAL(4)	Ports 0, 1 PWM0, PWM1	Total of all applicable pins				80	
		ΣIOAL(5)	Ports 2, P35, P36	Total of all applicable pins				45	
		ΣIOAL(6)	Ports P30 to P34	Total of all applicable pins				45	
		ΣIOAL(7)	Ports 2, 3	Total of all applicable pins				60	
Po	wer dissipation	Pd max	SQFP48(7×7)	Ta= -30 to +70°C				190	
	'		QIP48E(14×14)					390	mW
	erating ambient	Topr				-30		+70	
ICI Oti	nporature	Tota			1			1	°C

# **Absolute Maximum Ratings** at $Ta = 25^{\circ}C$ , $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Note 1-1: The mean output current is a mean value measured over 100ms.

Storage ambient

temperature

Tstg

+125

-55

						Specifi	Specification typ max		
Parameter	Symbol	Pin/Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit	
Operating	V <sub>DD</sub> (1)	V <sub>DD</sub> 1=V <sub>DD</sub> 2=V <sub>DD</sub> 3	0.294µs ≤ tCYC ≤ 200µs		4.0		5.5		
supply voltage	V <sub>DD</sub> (2)		0.367µs ≤ tCYC ≤ 200µs		3.0		5.5		
(Note 2-1)	V <sub>DD</sub> (3)		0.588µs ≤ tCYC ≤ 200µs		2.5		5.5		
Memory sustaining supply voltage	VHD	V <sub>DD</sub> 1=V <sub>DD</sub> 2=V <sub>DD</sub> 3	RAM and register contents sustained in HOLD mode.		2.0		5.5		
High level input voltage	V <sub>IH</sub> (1)	Ports 1, 2, 3 P71 to P73 P70 port input/ interrupt side PWM0, PWM1		2.5 to 5.5	0.3V <sub>DD</sub> +0.7		V <sub>DD</sub>		
	V <sub>IH</sub> (2)	Port 0		2.5 to 5.5	0.3V <sub>DD</sub> +0.7		V <sub>DD</sub>		
	V <sub>IH</sub> (3)	Port 70 watchdog timer side		2.5 to 5.5	0.9V <sub>DD</sub>		V <sub>DD</sub>	V	
	V <sub>IH</sub> (4)	XT1, XT2, CF1, RES		2.5 to 5.5	0.75V <sub>DD</sub>		V <sub>DD</sub>		
Low level input voltage	∨ <sub>IL</sub> (1)	Ports 1, 2, 3 P71 to P73		4.0 to 5.5	V <sub>SS</sub>		0.1V <sub>DD</sub> +0.4		
		P70 port input/ interrupt side PWM0, PWM1		2.5 to 4.0	V <sub>SS</sub>		0.2V <sub>DD</sub>		
	V <sub>IL</sub> (2)	Port 0		4.0 to 5.5	V <sub>SS</sub>		0.15V <sub>DD</sub> +0.4		
				2.5 to 4.0	V <sub>SS</sub>		0.2V <sub>DD</sub>		
	V <sub>IL</sub> (3)	Port 70 watchdog timer side		2.5 to 5.5	V <sub>SS</sub>		0.8V <sub>DD</sub> -1.0		
	V <sub>IL</sub> (4)	XT1, XT2, CF1, RES		2.5 to 5.5	V <sub>SS</sub>		0.25V <sub>DD</sub>		
Instruction cycle	tCYC			4.0 to 5.5	0.294		200		
time	(Note 2-2)			3.0 to 5.5	0.367		200	μs	
(Note 2-1)				2.5 to 5.5	0.588		200		
External system clock frequency	FEXCF	CF1	CF2 pin open     System clock frequency     division ratio=1/1	4.0 to 5.5	0.1		10		
			External system clock duty=50±5%	2.5 to 5.5	0.1		5	MHz	
			• CF2 pin open	4.0 to 5.5	0.2		20.4		
			<ul> <li>System clock frequency division ratio=1/2</li> </ul>	2.5 to 5.5	0.1		10		
Oscillation frequency	FmCF(1)	CF1, CF2	10MHz ceramic oscillation See Fig 1.	4.0 to 5.5		10			
range (Note 2-3)	FmCF(2)	CF1, CF2	8MHz ceramic oscillation See Fig 1.	3.0 to 5.5		8			
	FmCF(3)	CF1, CF2	5MHz ceramic oscillation See Fig 1.	2.5 to 5.5		5		MHz	
	FmRC		Internal RC oscillation	2.5 to 5.5	0.3	1.0	2.0		
	FmMRC		Frequency variable RC oscillation source oscillation	2.5 to 5.5		16			
	FsX'tal	XT1, XT2	32.768kHz crystal oscillation See Fig 2.	2.5 to 5.5		32.768		kHz	

# Allowable Operating Conditions at at $Ta = -30^{\circ}C$ to $+70^{\circ}C$ , $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Note 2-1: V<sub>DD</sub> must be held greater than or equal to 3.0V in the flash ROM onboard programming mode.

Note 2-2: Relationship between tCYC and oscillation frequency is 3/FmCF at a division ratio of 1/1 and 6/FmCF at a division ratio of 1/2.

Note 2-3: See Tables 1 and 2 for the oscillation constants.

Parameter	Symbol	Pin/Remarks	Conditions			Specifica	ation	
Parameter	Symbol	Pin/Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit
High level input current	I <sub>IH</sub> (1)	Ports 0, 1, 2, 3 Port 7 RES PWM0, PWM1	Output disabled Pull-up resistor off VIN=VDD (Including output Tr's off leakage current)	2.5 to 5.5			1	
	I <sub>IH</sub> (2)	XT1, XT2	For input port specification VIN=VDD	2.5 to 5.5			1	
	I <sub>IH</sub> (3)	CF1	VIN=V <sub>DD</sub>	2.5 to 5.5			15	
Low level input current	I <sub>IL</sub> (1)	Ports 0, 1, 2, 3 Port 7 RES PWM0, PWM1	Output disabled Pull-up resistor off VIN=VSS (Including output Tr's off leakage current)	2.5 to 5.5	-1			μA
	I <sub>IL</sub> (2)	XT1, XT2	For input port specification VIN=VSS	2.5 to 5.5	-1			
	I <sub>IL</sub> (3)	CF1	V <sub>IN</sub> =V <sub>SS</sub>	2.5 to 5.5	-15			
High level output voltage	V <sub>OH</sub> (1)	Ports 0, 1, 2, 3	I <sub>OH</sub> = -1mA	4.5 to 5.5	V <sub>DD</sub> -1			
	V <sub>OH</sub> (2)		I <sub>OH</sub> = -0.1mA	2.5 to 5.5	V <sub>DD</sub> -0.5			
	V <sub>OH</sub> (3)	P71 to P73 PWM0, PWM1, P05(System clock	I <sub>OH</sub> = -0.4mA	4.5 to 5.5	V <sub>DD</sub> -1			V
	V <sub>OH</sub> (4)		I <sub>OH</sub> = -6mA	4.5 to 5.5	V <sub>DD</sub> -1			
	V <sub>OH</sub> (5)		I <sub>OH</sub> = -1.6mA	4.5 to 5.5	V <sub>DD</sub> -0.4			
	V <sub>OH</sub> (6)	output function used)	I <sub>OH</sub> = -1mA	2.5 to 5.5	V <sub>DD</sub> -0.4			
Low level output	V <sub>OL</sub> (1)	Ports 0, 1, 2, 3,	I <sub>OL</sub> =10mA	4.5 to 5.5			1.5	
voltage	V <sub>OL</sub> (2)	PWM0, PWM1,	I <sub>OL</sub> =1.6mA	4.5 to 5.5			0.4	
	V <sub>OL</sub> (3)	XT2	I <sub>OL</sub> =1mA	2.5 to 5.5			0.4	
	V <sub>OL</sub> (4)	P00, P01	I <sub>OL</sub> =30mA	4.5 to 5.5			1.5	
	V <sub>OL</sub> (5)	Port 7	I <sub>OL</sub> =1mA	2.5 to 5.5			0.4	
Pull-up resistance	Rpu(1)	Ports 0, 1, 2, 3 Port 7	V <sub>OH</sub> =0.9V <sub>DD</sub>	4.5 to 5.5	15	35	80	kO
	Rpu(2)	Ports 0, 1, 2, 3 Port 7	V <sub>OH</sub> =0.9V <sub>DD</sub>	2.5 to 4.5	18	50	150	kΩ
Hysteresis voltage	VHYS	RES Ports 1, 2, 7		2.5 to 5.5		0.1V <sub>DD</sub>		v
Pin capacitance	СР	All pins	For pins other than that under test: V <sub>IN</sub> =V <sub>SS</sub> f=1MHz Ta=25°C	2.5 to 5.5		10		pF

# **Electrical Characteristics** at $Ta = -30^{\circ}C$ to $+70^{\circ}C$ , $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

# Serial Input/Output Characteristics at Ta = -30°C to +70°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$ 1. SIO0 Serial I/O Characteristics (Note 4-1-1)

		Parameter	Symbol	Pin/Remarks	Conditions			Speci	cification	
	F	Parameter	Symbol	Pin/Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit
		Frequency	tSCK(1)	SCK0(P12)	See Fig. 6.		2			
	×	Low level pulse width	tSCKL(1)				1			
	Input clock	High level pulse width	tSCKH(1)			2.5 to 5.5	1			tCYC
Serial clock	L		tSCKHA(1)		Continuous data transmission/reception mode     See Fig. 6.     (Note 4-1-2)		4			
Serial		Frequency	tSCK(2)	SCK0(P12)	CMOS output selected     See Fig. 6.		4/3			
	ock	Low level pulse width				1/2		tSCK		
	Output clock	High level pulse width	tSCKH(2)			2.5 to 5.5		1/2		ISON
	õ		tSCKHA(2)		Continuous data transmission/reception mode CMOS output selected See Fig. 6.		tSCKH(2) +2tCYC		tSCKH(2) +(10/3) tCYC	tCYC
Serial input	Da	ta setup time	tsDI(1)	SB0(P11), SI0(P11)	Must be specified with respect to rising edge of SIOCLK.	2.5 to 5.5	0.03			
Serial	Da	Data hold time thDI(1)		vold time thDI(1) • See Fig. 6.	2.5 to 5.5	0.03				
	Input clock	Output delay time	tdD0(1)	SO0(P10), SB0(P11)	Continuous data transmission/reception mode     (Note 4-1-3)	2.5 to 5.5			(1/3)tCYC +0.05	μs
Serial output	Input		tdD0(2)		Synchronous 8-bit mode     (Note 4-1-3)	2.5 to 5.5			1tCYC +0.05	
Seris	Output clock		tdD0(3)		(Note 4-1-3)	2.5 to 5.5			(1/3)tCYC +0.05	

Note 4-1-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-1-2: To use serial-clock-input in continuous trans/rec mode, a time from SIORUN being set when serial clock is "H" to the first negative edge of the serial clock must be longer than tSCKHA.

Note 4-1-3: Must be specified with respect to falling edge of SIOCLK. Must be specified as the time to the beginning of output state change in open drain output mode. See Fig. 6.

# 2. SIO1 Serial I/O Characteristics (Note 4-2-1)

		Parameter	Symbol	Pin/Remarks	Conditions			Speci	fication	
		Parameter	Symbol	PIN/Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit
	×	Frequency	tSCK(3)	SCK1(P15)	See Fig. 6.		2			
	Input clock	Low level pulse width	tSCKL(3)			2.5 to 5.5	1			
Serial clock	-I	High level pulse width	tSCKH(3)				1			tCYC
Serial	ş	Frequency	tSCK(4)	SCK1(P15)	CMOS output selected     See Fig. 6.		2			
	Output clock	Low level pulse width	tSCKL(4)			2.5 to 5.5		1/2		tSCK
	õ	High level pulse width	tSCKH(4)					1/2		ISCK
Serial input	Da	ta setup time	tsDI(2)	SB1(P14), SI1(P14)	Must be specified with respect to rising edge of SIOCLK.	2.5 to 5.5	0.03			
Serial	Da	ata hold time	thDI(2)		• See Fig. 6.	2.5 to 5.5	0.03			
Serial output	Οι	itput delay time	tdD0(4)	SO1(P13), SB1(P14)	<ul> <li>Must be specified with respect to falling edge of SIOCLK.</li> <li>Must be specified as the time to the beginning of output state change in open drain output mode.</li> <li>See Fig. 6.</li> </ul>	2.5 to 5.5			(1/3)tCYC +0.05	μs

Note 4-2-1: These specifications are theoretical values. Add margin depending on its use.

### **Pulse Input Conditions** at $Ta = -30^{\circ}C$ to $+70^{\circ}C$ , $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Deremeter	Cumbol	Din/Domorko	Conditions	_		Specif	ication	
Parameter	Symbol	Pin/Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit
High/low level	tPIH(1)	INT0(P70),	Interrupt source flag can be set.					
pulse width	tPIL(1)	INT1(P71),	• Event inputs for timer 0 or 1 are					
		INT2(P72),	enabled.	2.5 to 5.5	1			
		INT4(P20 to P23),						
		INT5(P24 to P27)						
	tPIH(2)	INT3(P73) when	Interrupt source flag can be set.					
	tPIL(2)	noise filter time	Event inputs for timer 0 are	2.5 to 5.5	2			101/0
		constant is 1/1	enabled.					tCYC
	tPIH(3)	INT3(P73) when	Interrupt source flag can be set.					
	tPIL(3)	noise filter time	Event inputs for timer 0 are	2.5 to 5.5	64			
		constant is 1/32	enabled.					
	tPIH(4)	INT3(P73) when	Interrupt source flag can be set.					
	tPIL(4)	noise filter time	Event inputs for timer 0 are	2.5 to 5.5	256			
		constant is 1/128	enabled.					
	tPIL(5)	RES	Resetting is enabled.	2.5 to 5.5	200			μs

# AD Converter Characteristics at $\mathbf{V}_{SS}\mathbf{1}=\mathbf{V}_{SS}\mathbf{2}=\mathbf{V}_{SS}\mathbf{3}=\mathbf{0}\mathbf{V}$

<12-bits AD Converter Mode / Ta=  $-10^{\circ}$ C to  $+50^{\circ}$ C>

Deremeter	Cumhal	Pin/Remarks	Conditions			Speci	fication	
Parameter	Symbol	PIN/Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit
Resolution	Ν	AN0(P00) to		4.75 to 5.25		12		bit
Absolute accuracy	ET	AN7(P07)	(Note 6-1)	4.75 to 5.25			T.B.D	LSB
Conversion time	TCAD	AN8(P70) AN9(P71) AN10(XT1)	See conversion time calculation formulas. (Note 6-2)	4.75 to 5.25	38.5		90	μs
Analog input voltage range	VAIN	AN11(XT2)		4.75 to 5.25	V <sub>SS</sub>		V <sub>DD</sub>	V
Analog port input	IAINH		VAIN=V <sub>DD</sub>	4.75 to 5.25			1	
current	IAINL		VAIN=V <sub>SS</sub>	4.75 to 5.25	-1			μA

### <8-bits AD Converter Mode / Ta= -30°C to +70°C>

Descention	Quarte el	Dia /De as e alua	Conditions			Speci	fication		
Parameter	Symbol	Pin/Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit	
Resolution	Ν	AN0(P00) to		3.0 to 5.5		8		bit	
Absolute accuracy	ET	AN7(P07)	(Note 6-1)	3.0 to 5.5			±1.5	LSB	
Conversion time	TCAD	AN8(P70) AN9(P71)	See conversion time calculation	4.5 to 5.5	22.5		90		
		AN10(XT1)	formulas. (Note 6-2)	3.0 to 5.5	45		90	μs	
Analog input voltage range	VAIN	AN11(XT2)		3.0 to 5.5	V <sub>SS</sub>		V <sub>DD</sub>	V	
Analog port input	IAINH		VAIN=V <sub>DD</sub>	3.0 to 5.5			1		
current	IAINL		VAIN=V <sub>SS</sub>	3.0 to 5.5	-1			μA	

Conversion time calculation formulas:

12-bits AD Converter Mode: TCAD (Conversion time) =  $((52/(\text{division ratio}))+2) \times (1/3) \times \text{tCYC}$ 

8-bits AD Converter Mode: TCAD (Conversion time) =  $((32/(\text{division ratio}))+2) \times (1/3) \times \text{tCYC}$ 

- Note 6-1: The quantization error (±1/2LSB) must be excluded from the absolute accuracy. The absolute accuracy must be measured in the microcontroller's state in which no I/O operations occur at the pins adjacent to the analog input channel.
- Note 6-2: The conversion time refers to the period from the time an instruction for starting a conversion process till the time the conversion results register(s) are loaded with a complete digital conversion value corresponding to the analog input value.

The conversion time is 2 times the normal-time conversion time when:

• The first AD conversion is performed in the 12-bit AD conversion mode after a system reset.

• The first AD conversion is performed after the AD conversion mode is switched from 8-bit to 12-bit conversion mode.

<b>Consumption Current Characteristics</b> at Ta =	$= -30^{\circ}$ C to $+70^{\circ}$ C, VSS1 $= $ VSS2 $= $ VSS3 $= 0$ V
--	--

Deremeter	Cumhal	Pin/	Conditions			Specific	cation	
Parameter	Symbol	Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	Max	unit
Normal mode consumption current (Note 7-1)	IDDOP(1)	V <sub>DD</sub> 1 =V <sub>DD</sub> 2 =V <sub>DD</sub> 3	<ul> <li>FmCF=10MHz ceramic oscillation mode</li> <li>FsX'tal=32.768kHz crystal oscillation mode</li> <li>System clock set to 10MHz side</li> <li>Internal RC oscillation stopped</li> <li>Frequency variable RC oscillation stopped</li> <li>1/1 frequency division ratio</li> </ul>	4.0 to 5.5		7.7	20	
	IDDOP(2)	-	CF1=20MHz external clock     FsX'tal=32.768kHz crystal oscillation mode     System clock set to CF1 side     Internal RC oscillation stopped     Frequency variable RC oscillation stopped     1/2 frequency division ratio	4.0 to 5.5		8.7	20	
	IDDOP(3)		FmCF=5MHz ceramic oscillation mode     FsX'tal=32.768kHz crystal oscillation mode     System clock set to 5MHz side	4.5 to 5.5		5.2	12	mA
	IDDOP(4)		<ul> <li>Internal RC oscillation stopped</li> <li>Frequency variable RC oscillation stopped</li> <li>1/1 frequency division ratio</li> </ul>	4.5 to 5.5		3.5	10	
	IDDOP(5) IDDOP(6) IDDOP(7)		<ul> <li>FmCF=0Hz (oscillation stopped)</li> <li>FsX'tal=32.768kHz crystal oscillation mode</li> <li>System clock set to internal RC oscillation</li> </ul>	4.5 to 5.5		0.7	2.9	
			Frequency variable RC oscillation stopped     1/2 frequency division ratio	2.5 to 4.5		0.4	2.1	
			FmCF=0Hz (oscillation stopped)     FsX'tal=32.768kHz crystal oscillation mode     Internal RC oscillation stopped	4.5 to 5.5		1.4	5.3	
	IDDOP(9) FrwCF= • FsX'tal		<ul> <li>System clock set to 1MHz with frequency variable RC oscillation</li> <li>1/2 frequency division ratio</li> </ul>	2.5 to 4.5		0.9	3.9	
			<ul> <li>FmCF=0Hz (oscillation stopped)</li> <li>FsX'tal=32.768kHz crystal oscillation mode</li> <li>System clock set to 32.768kHz side</li> </ul>	4.5 to 5.5		34	90	
	IDDOP(10)		<ul> <li>Internal RC oscillation stopped</li> <li>Frequency variable RC oscillation stopped</li> <li>1/2 frequency division ratio</li> </ul>	2.5 to 4.5		23	70	μ/

Note 7-1: The consumption current value includes none of the currents that flow into the output Tr and internal pull-up resistors.

Continued on next page.

Parameter	Symbol	Pin/	Conditions			Specific	cation	
Falameter	Symbol	remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit
HALT mode consumption current (Note 7-1)	IDDHALT(1)	V <sub>DD</sub> 1 =V <sub>DD</sub> 2 =V <sub>DD</sub> 3	HALT mode     FmCF=10MHz ceramic oscillation mode     FsX'tal=32.768kHz crystal oscillation mode     System clock set to 10MHz side     Internal RC oscillation stopped     Frequency variable RC oscillation stopped     1/1 frequency division ratio	4.0 to 5.5		3.1	6	
	IDDHALT(2)	-	HALT mode     CF1=20MHz external clock     FsX'tal=32.768kHz crystal oscillation mode     System clock set to CF1 side     Internal RC oscillation stopped     Frequency variable RC oscillation stopped     1/2 frequency division ratio	4.0 to 5.5		4	9	
	IDDHALT(3)		HALT mode     FmCF=5MHz ceramic oscillation mode     FsX'tal=32.768kHz crystal oscillation mode	4.5 to 5.5		1.9	4.1	mA
	IDDHALT(4)		<ul> <li>System clock set to 5MHz side</li> <li>Internal RC oscillation stopped</li> <li>Frequency variable RC oscillation stopped</li> <li>1/1 frequency division ratio</li> </ul>	2.5 to 4.5		1.3	3.0	
	IDDHALT(5)		HALT mode     FmCF=0Hz (oscillation stopped)     FsX'tal=32.768kHz crystal oscillation mode	4.5 to 5.5		0.35	1.4	
	IDDHALT(6)		System clock set to internal RC oscillation     Frequency variable RC oscillation stopped     1/2 frequency division ratio	2.5 to 4.5		0.25	0.95	
	IDDHALT(7)		HALT mode     FmCF=0Hz (oscillation stopped)     FsX'tal=32.768kHz crystal oscillation mode     Internal RC oscillation stopped	4.5 to 5.5		1.1	4	
	IDDHALT(8)		System clock set to 1MHz with frequency variable RC oscillation     1/2 frequency division ratio	2.5 to 4.5		0.8	3.0	
	IDDHALT(9)		HALT mode     FmCF=0Hz (oscillation stopped)     FsX'tal=32.768kHz crystal oscillation mode     System stack set to 22.769kHz cride	4.5 to 5.5		20	51	
	IDDHALT(10)		<ul> <li>System clock set to 32.768kHz side</li> <li>Internal RC oscillation stopped</li> <li>Frequency variable RC oscillation stopped</li> <li>1/2 frequency division ratio</li> </ul>	2.5 to 4.5		18	35	
HOLD mode	IDDHOLD(1)	V <sub>DD</sub> 1	HOLD mode	4.5 to 5.5		0.04	11	μA
consumption	IDDHOLD(2)	-	• CF1=V <sub>DD</sub> or open	2.5 to 4.5		0.01	8	
current Timer HOLD mode consumption	IDDHOLD(3)	V <sub>DD</sub> 1	(External clock mode) Timer HOLD mode • CF1=V <sub>DD</sub> or open	4.5 to 5.5		17	50	
current	IDDHOLD(4)		<ul> <li>(External clock mode)</li> <li>FsX'tal=32.768kHz crystal oscillation mode</li> </ul>	2.5 to 4.5		12	30	

Note 7-1: The consumption current value includes none of the currents that flow into the output Tr and internal pull-up resistors.

Parameter	Sumbol	Pin/Remarks	Conditions		fication	_		
Parameter	Symbol	Pin/Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit
Onboard programming current	IDDFW	V <sub>DD</sub> 1	<ul><li>128-byte programming</li><li>Erasing current included</li></ul>	3.0 to 5.5		25	40	mA
Programming time	tFW		<ul> <li>128-byte programming</li> <li>Erasing current included</li> <li>Time for setting up 128-byte data is excluded.</li> </ul>	3.0 to 5.5		22.5	45	ms

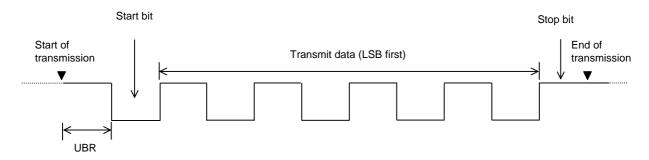
# **UART (Full duplex) Operating Conditions** at $Ta = -30^{\circ}C$ to $+70^{\circ}C$ , $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Deremeter	Cumbal	Din /Demorke	Conditions		Specification				
Parameter	Symbol	Pin/Remarks	Conditions	V <sub>DD</sub> [V]	min	typ	max	unit	
Transfer rate	UBR	P20, P21		2.5 to 5.5	16/3		8192/3	tCYC	

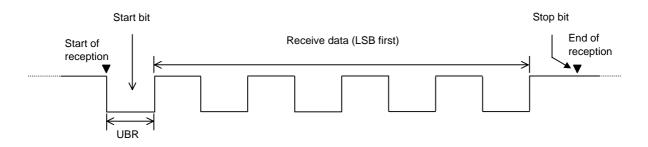
Data length: 7, 8, and 9 bits (LSB first)

Stop bits:1-bit (2-bit in continuous data transmission)Parity bits:Non

### Example of Continuous 8-bit Data Transmission Mode Processing (first transmit data=55H)



### Example of Continuous 8-bit Data Reception Mode Processing (first receive data=55H)



# **Characteristics of a Sample Main System Clock Oscillation Circuit**

Given below are the characteristics of a sample main system clock oscillation circuit that are measured using a SANYO-designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Nominal			Circuit Constant				Operating Voltage	Oscillation S	Stabilization ne	Remarks
Frequency	Vendor Name	Oscillator Name	C1 [pF]	C2 [pF]	Rf [Ω]	Rd1 [Ω]	Range [V]	typ [ms]	max [ms]	Remarks
10MHz	MURATA	CSTCE10M0G52-R0	(10)	(10)	Open	680	4.0 to 5.5	0.1	0.5	Internal C1, C2
TUMHZ	MURATA	CSTCE10M0G52-B0	(10)	(10)	Open	680	4.0 to 5.5	0.1	0.5	(SMD type)
01411-		CSTCE8M00G52-R0	(10)	(10)	Open	1.0k	3.0 to 5.5	0.1	0.5	Internal C1, C2
8MHz	MURATA	CSTCE8M00G52-B0	(10)	(10)	Open	1.0k	3.0 to 5.5	0.1	0.5	(SMD type)
5MHz	MURATA	CSTCR5M00G53-R0	(15)	(15)	Open	2.2k	2.5 to 5.5	0.2	0.6	Internal C1, C2
SIVIEZ	MURATA	CSTCR5M00G53-B0	(15)	(15)	Open	2.2k	2.5 to 5.5	0.2	0.6	(SMD type)

Table 1 Characteristics of a Sample Main System Clock Oscillator Circuit with a Ceramic Oscillator

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after  $V_{DD}$  goes above the operating voltage lower limit (see Figure 4).

It is recommended to insert feedback resister(Rf:1MQ) when power supply voltage is used around 2.5V.

# Characteristics of a Sample Subsystem Clock Oscillator Circuit

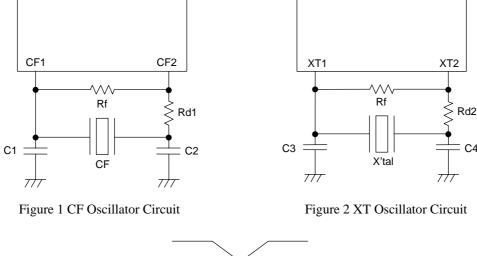
Given below are the characteristics of a sample subsystem clock oscillation circuit that are measured using a SANYOdesignated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 2 Characteristics of a Sample Subsystem Clock Osemator Credit with a Crystal Osemator											
Nominal	Vendor Name	Ossillator Nama		Circuit	Constant		Operating Voltage	Oscillation Stabilization Time		Domorko	
Frequency	vendor Name	Oscillator Name	C3 [pF]	C4 [pF]	Rf [Ω]	Rd2 [Ω]	Range [V]	typ [s]	max [s]	Remarks	
32.768kHz	EPSON TOYOCOM	MC-306	18	18	Open	510k	2.5 to 5.5	1.1	3.0	Applicable CL value=12.5pF	

Table 2 Characteristics of a Sample Subsystem Clock Oscillator Circuit with a Crystal Oscillator

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after the instruction for starting the subclock oscillation circuit is executed and to the time interval that is required for the oscillation to get stabilized after the HOLD mode is reset (see Figure 4).

Note: The components that are involved in oscillation should be placed as close to the IC and to one another as possible because they are vulnerable to the influences of the circuit pattern.



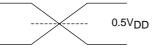
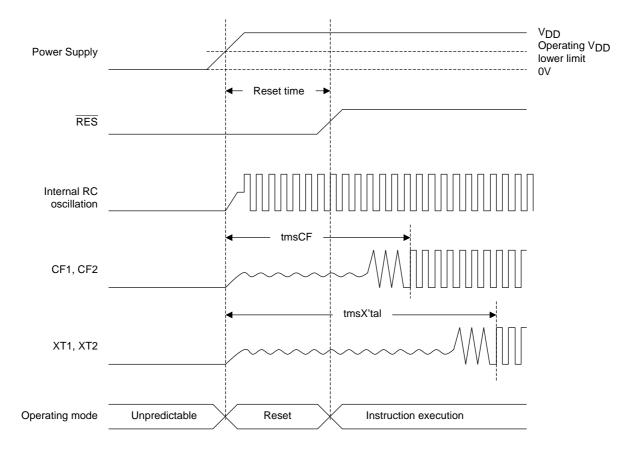
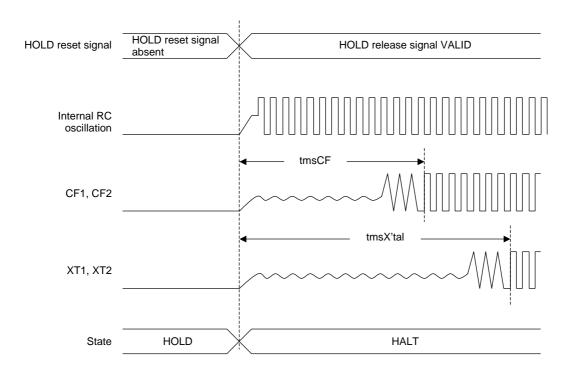


Figure 3 AC Timing Measurement Point

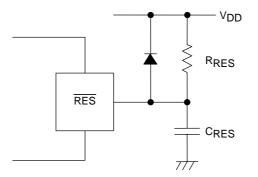


Reset Time and Oscillation Stabilization Time



HOLD Reset Signal and Oscillation Stabilization Time

Figure 4 Oscillation Stabilization Times



(Note)

Determine the value of  $C_{RES}$  and  $R_{RES}$  so that the reset signal is present for a period of 200 $\mu$ s after the supply voltage goes beyond the lower limit of the IC's operating voltage.

Figure 5 Reset Circuit

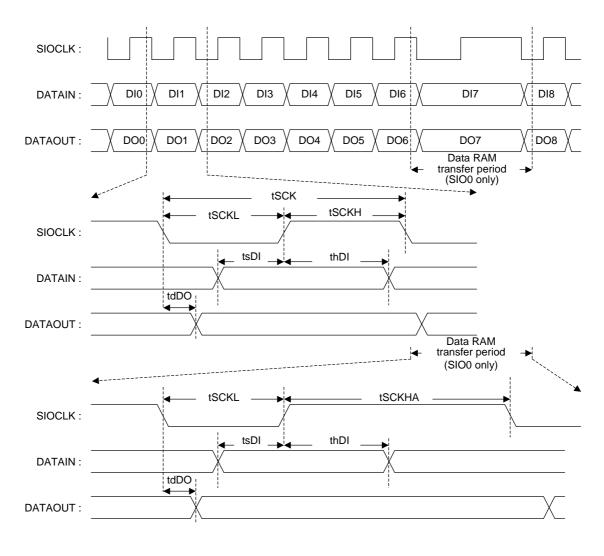


Figure 6 Serial I/O Output Waveforms

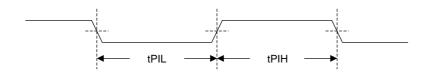


Figure 7 Pulse Input Timing Signal Waveform

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